



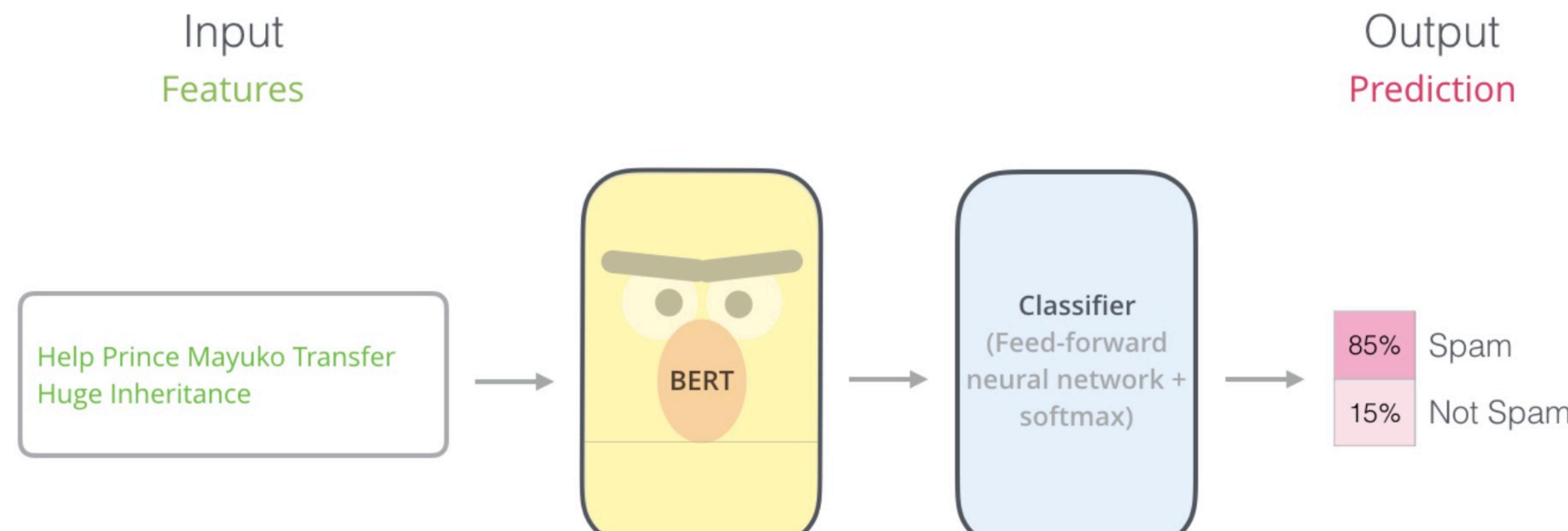
BERT: Pre-training of Deep Bidirectional Transformers for Language Understanding

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592 group

Outline

- Introduction to NLP
- BERT Model
- Conclusion

Introduction to NLP



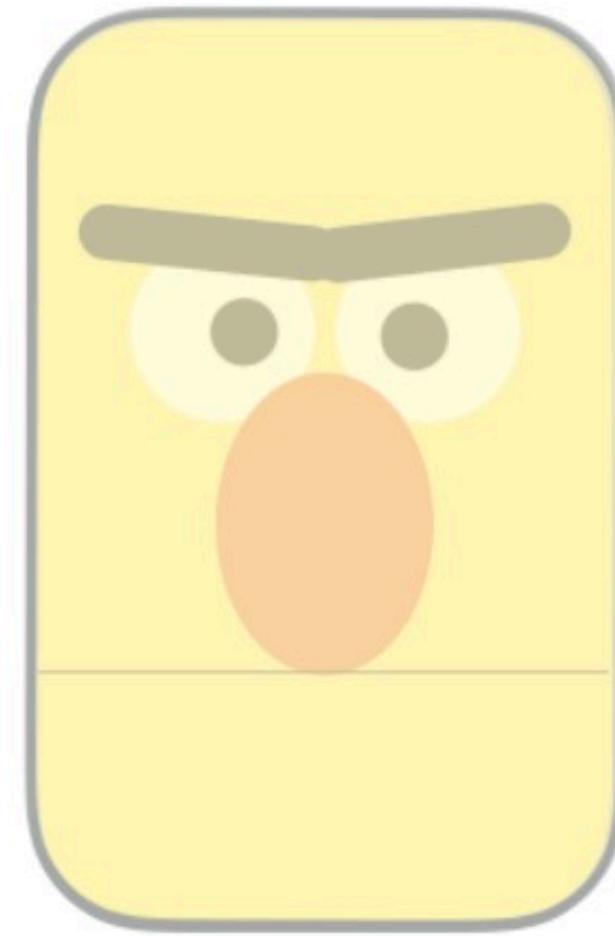
<http://jalammar.github.io/illustrated-bert/>

Introduction to NLP

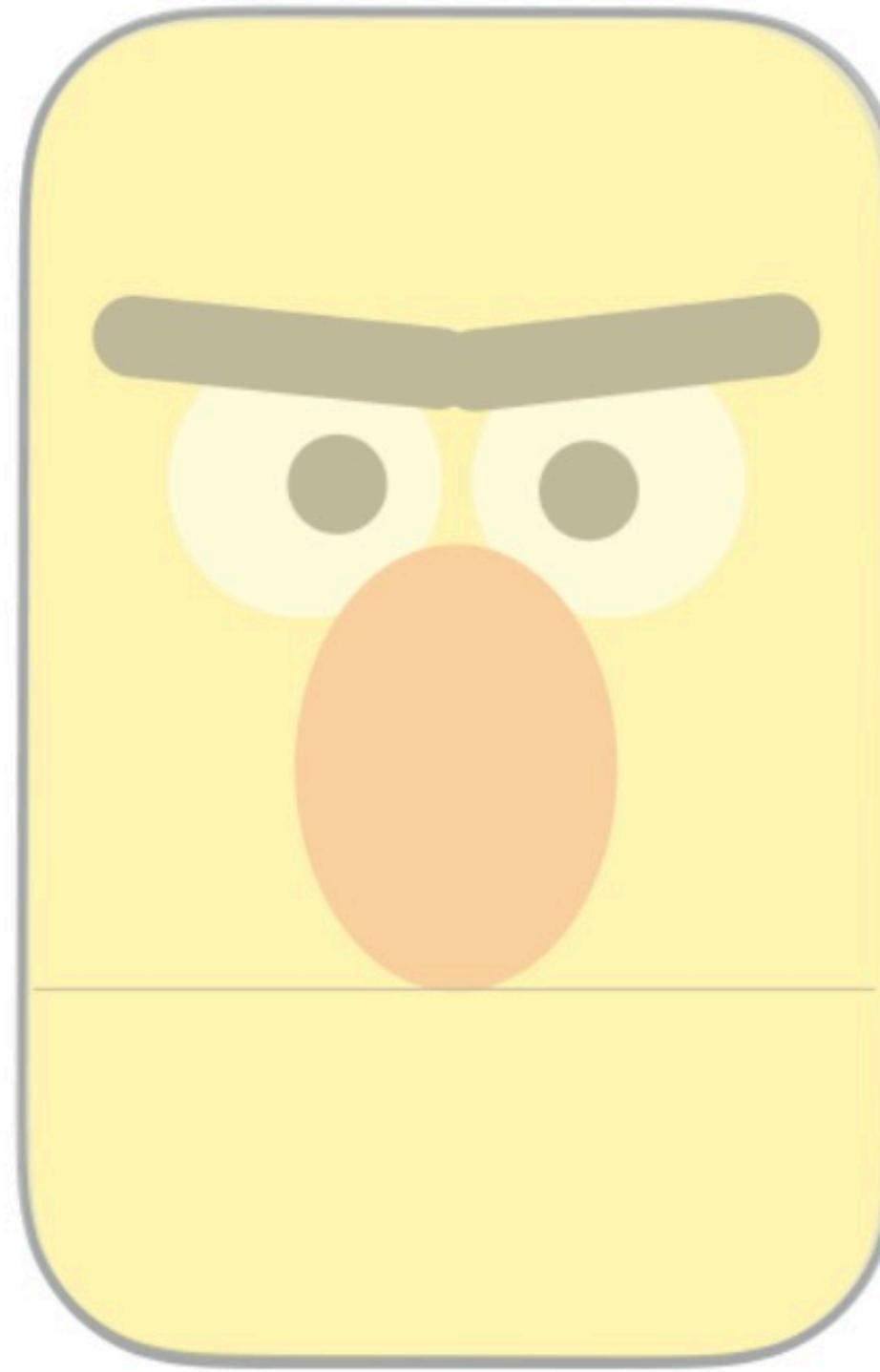
Email message	Class
Buy these pills	Spam
Win cash prizes	Spam
Dear Mr. Atreides, please find attached...	Not Spam

<http://jalammar.github.io/illustrated-bert/>

BERT Model

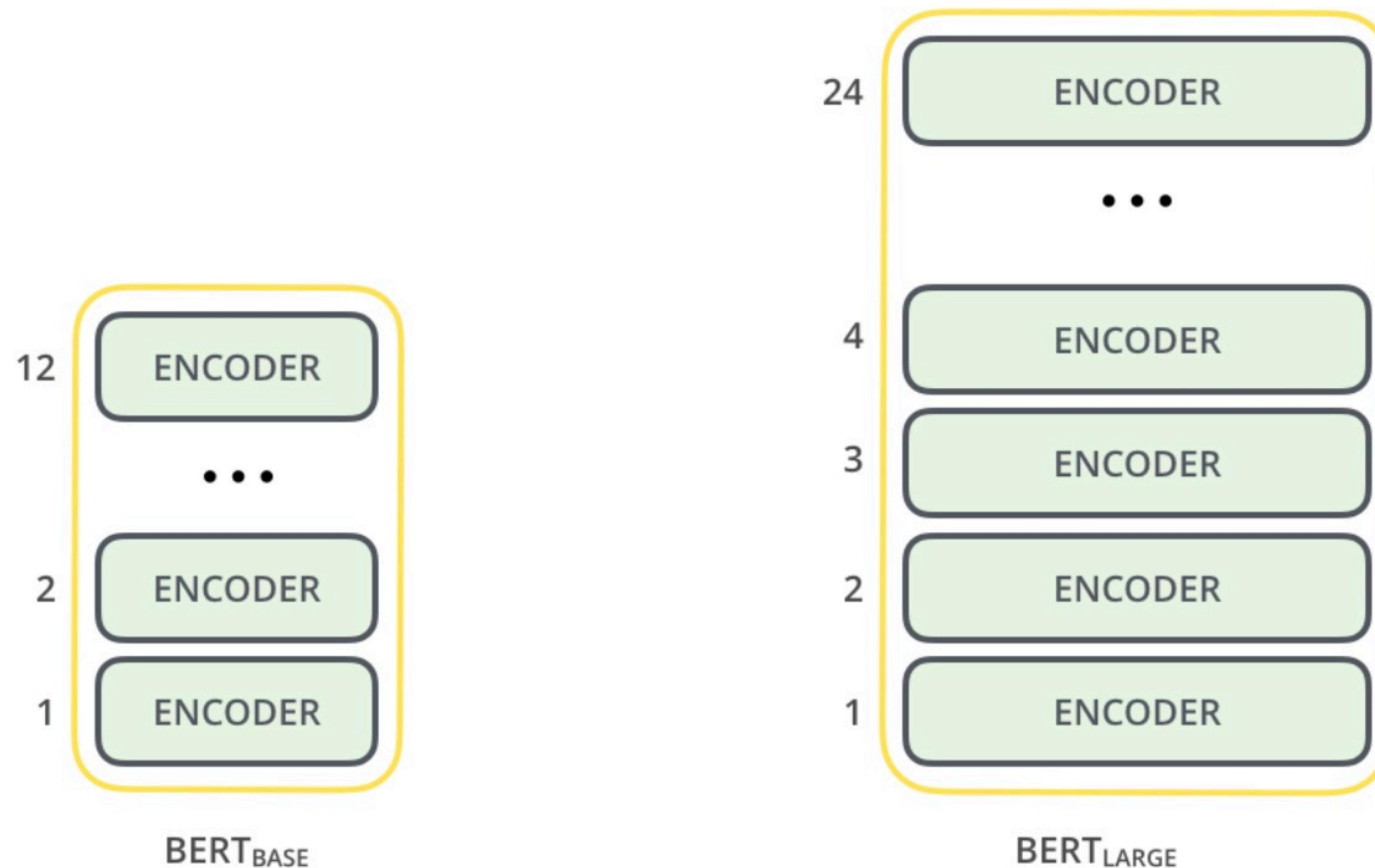


BERT_{BASE}



BERT_{LARGE}

BERT Model

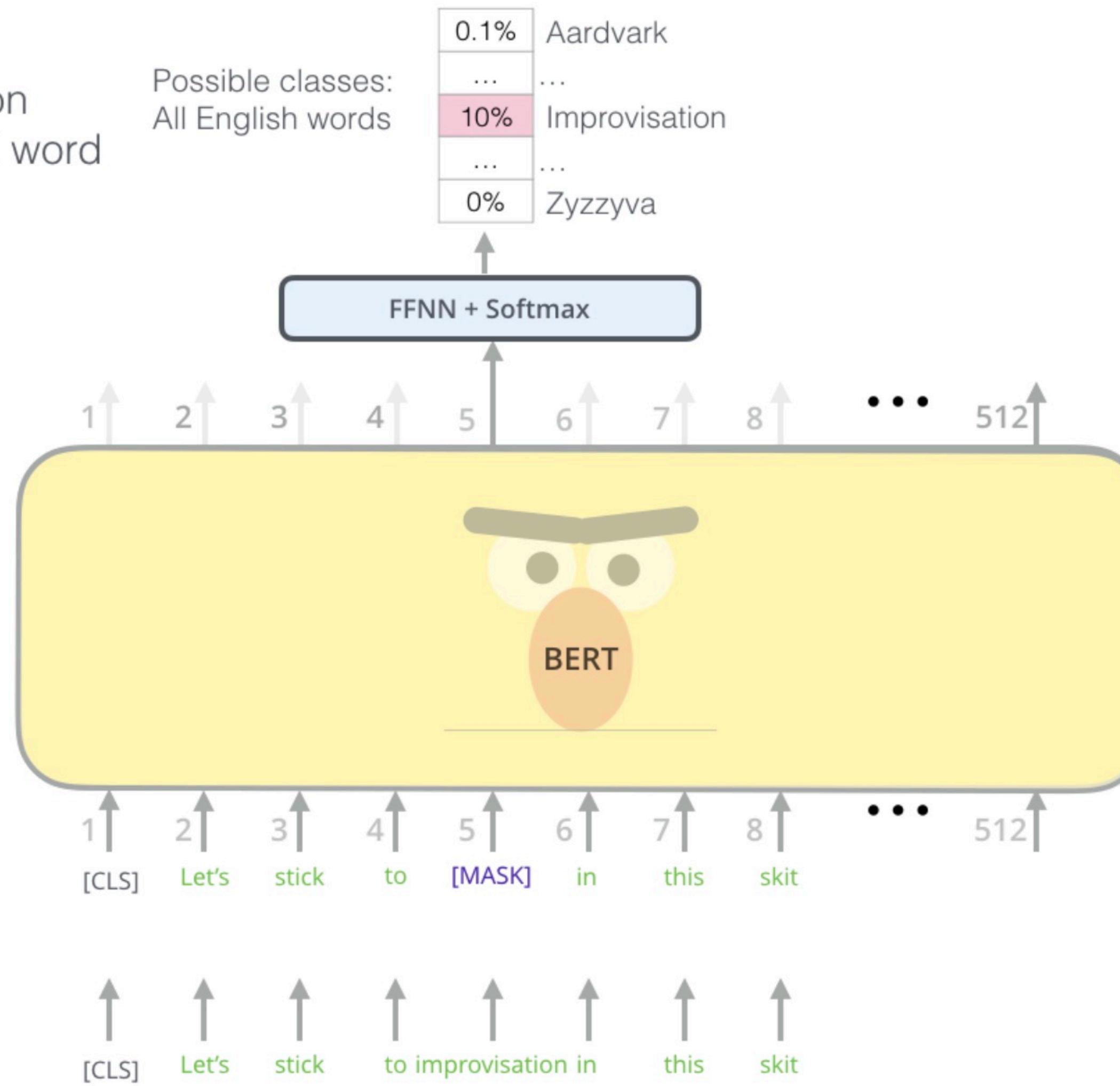


BERT Model

Use the output of the masked word's position to predict the masked word

Randomly mask 15% of tokens

Input



BERT Model

System	MNLI-(m/mm)	QQP	QNLI	SST-2	CoLA	STS-B	MRPC	RTE	Average
	392k	363k	108k	67k	8.5k	5.7k	3.5k	2.5k	-
Pre-OpenAI SOTA	80.6/80.1	66.1	82.3	93.2	35.0	81.0	86.0	61.7	74.0
BiLSTM+ELMo+Attn	76.4/76.1	64.8	79.9	90.4	36.0	73.3	84.9	56.8	71.0
OpenAI GPT	82.1/81.4	70.3	88.1	91.3	45.4	80.0	82.3	56.0	75.2
BERT _{BASE}	84.6/83.4	71.2	90.1	93.5	52.1	85.8	88.9	66.4	79.6
BERT _{LARGE}	86.7/85.9	72.1	91.1	94.9	60.5	86.5	89.3	70.1	81.9

Table 1: GLUE Test results, scored by the GLUE evaluation server. The number below each task denotes the number of training examples. The “Average” column is slightly different than the official GLUE score, since we exclude the problematic WNLI set. OpenAI GPT = (L=12, H=768, A=12); BERT_{BASE} = (L=12, H=768, A=12); BERT_{LARGE} = (L=24, H=1024, A=16). BERT and OpenAI GPT are single-model, single task. All results obtained from <https://gluebenchmark.com/leaderboard> and <https://blog.openai.com/language-unsupervised/>.

Summary

- The Illustrated BERT, ELMo, and co.: <http://jalammar.github.io/illustrated-bert/>
- About BERT in Google AI Blog: <https://ai.googleblog.com/2018/11/open-sourcing-bert-state-of-art-pre.html>
- Bert image's source: <https://twitter.com/bertsesame>

Conclusion

- Proposed and trained model is a **huge improvement** in the field of Natural Language Processing
- It makes the future in which **people and robots** can freely interact with each other much closer to nowadays